



1
00:00:07,349 --> 00:00:05,110
good day and welcome to the kennedy

2
00:00:09,430 --> 00:00:07,359
space center i am d wayne washington

3
00:00:11,270 --> 00:00:09,440
from the office of communications at

4
00:00:13,350 --> 00:00:11,280
nasa's goddard space flight center in

5
00:00:15,589 --> 00:00:13,360
greenbelt maryland today we're here to

6
00:00:17,349 --> 00:00:15,599
talk about the robotic refueling mission

7
00:00:19,510 --> 00:00:17,359
the module to be carried on the final

8
00:00:21,830 --> 00:00:19,520
shuttle mission here to explain the

9
00:00:24,390 --> 00:00:21,840
mission to my left

10
00:00:26,150 --> 00:00:24,400
frank cepellini

11
00:00:28,710 --> 00:00:26,160
project manager for the satellite

12
00:00:30,870 --> 00:00:28,720
servicing capabilities office at nasa's

13
00:00:35,990 --> 00:00:30,880

goddard space flight center

14
00:00:42,709 --> 00:00:39,350
matthew caron mission operations manager

15
00:00:46,950 --> 00:00:42,719
canadian space agency

16
00:00:50,950 --> 00:00:49,190
and finally we have ben reed deputy

17
00:00:53,430 --> 00:00:50,960
project manager for the satellite

18
00:00:55,750 --> 00:00:53,440
servicing capabilities office at nasa's

19
00:00:57,670 --> 00:00:55,760
goddard space flight center we'll begin

20
00:00:59,990 --> 00:00:57,680
with sepi

21
00:01:01,750 --> 00:01:00,000
well thank you for coming

22
00:01:03,590 --> 00:01:01,760
i look around the room and i see a lot

23
00:01:05,910 --> 00:01:03,600
of familiar faces

24
00:01:08,789 --> 00:01:05,920
we've been here for the last 20 years if

25
00:01:11,190 --> 00:01:08,799
you all remember with repair activities

26
00:01:13,670 --> 00:01:11,200
human repair activities on hubble

27
00:01:17,510 --> 00:01:13,680
but then i really started with you all

28
00:01:20,630 --> 00:01:17,520
back in that with kennedy back in 1984

29
00:01:23,670 --> 00:01:20,640
where we robotically captured solar max

30
00:01:24,390 --> 00:01:23,680
and then with humans repaired solar max

31
00:01:26,950 --> 00:01:24,400
so

32
00:01:29,270 --> 00:01:26,960
the servicing capabilities

33
00:01:31,590 --> 00:01:29,280
primarily vested with humans and with

34
00:01:33,749 --> 00:01:31,600
robotics started way back

35
00:01:35,670 --> 00:01:33,759
some 35 years ago

36
00:01:37,670 --> 00:01:35,680
and the interesting part about it is

37
00:01:40,469 --> 00:01:37,680
here we are today

38
00:01:43,590 --> 00:01:40,479

opening up a brand new era

39

00:01:45,830 --> 00:01:43,600
and i underscore brand new era

40

00:01:48,710 --> 00:01:45,840
in servicing of

41

00:01:50,950 --> 00:01:48,720
expensive satellite systems

42

00:01:54,870 --> 00:01:50,960
through the use of robotics

43

00:01:57,190 --> 00:01:54,880
and that's represents a new major

44

00:01:59,749 --> 00:01:57,200
initiative and capability

45

00:02:01,590 --> 00:01:59,759
that the global space community is now

46

00:02:02,950 --> 00:02:01,600
stepping up to and i want to introduce

47

00:02:06,230 --> 00:02:02,960
our partner

48

00:02:08,790 --> 00:02:06,240
who we've worked hard with at canadian

49

00:02:10,949 --> 00:02:08,800
space agency matthew carone and the

50

00:02:13,350 --> 00:02:10,959
canadian space agency that have been the

51

00:02:15,430 --> 00:02:13,360

other part of this u.s

52

00:02:17,030 --> 00:02:15,440

canadian partnership and they are the

53

00:02:19,910 --> 00:02:17,040

folks that build

54

00:02:22,790 --> 00:02:19,920

the robotic arm the canadian robotic arm

55

00:02:25,110 --> 00:02:22,800

for iss and spit them

56

00:02:27,270 --> 00:02:25,120

did what we affectionately called the

57

00:02:28,710 --> 00:02:27,280

dexter robot which we will be using on

58

00:02:33,430 --> 00:02:28,720

this mission

59

00:02:34,869 --> 00:02:33,440

is going to talk about the details as to

60

00:02:38,309 --> 00:02:34,879

how it works

61

00:02:40,949 --> 00:02:38,319

but it focuses on two principal issues

62

00:02:43,350 --> 00:02:40,959

the first principle issue is the ability

63

00:02:45,670 --> 00:02:43,360

to capture and repair

64

00:02:48,150 --> 00:02:45,680

satellites that have never been designed

65

00:02:49,270 --> 00:02:48,160

for in-orbit repair or capture

66

00:02:52,070 --> 00:02:49,280

if you remember

67

00:02:54,070 --> 00:02:52,080

hubble and solar max had elements of

68

00:02:55,110 --> 00:02:54,080

designability incorporated into their

69

00:02:57,990 --> 00:02:55,120

systems

70

00:03:00,869 --> 00:02:58,000

where in fact they were amenable to

71

00:03:04,550 --> 00:03:00,879

repair via humans

72

00:03:06,869 --> 00:03:04,560

in the present state there's over 370

73

00:03:08,869 --> 00:03:06,879

semi-commercial communication satellites

74

00:03:09,830 --> 00:03:08,879

in geosynchronous orbit and over a

75

00:03:11,910 --> 00:03:09,840

hundred

76
00:03:13,910 --> 00:03:11,920
government-owned systems none of which

77
00:03:15,589 --> 00:03:13,920
have been designed for repair

78
00:03:17,589 --> 00:03:15,599
yet what we're trying to do and

79
00:03:18,949 --> 00:03:17,599
demonstrate is that the

80
00:03:20,470 --> 00:03:18,959
technology

81
00:03:21,990 --> 00:03:20,480
and capability

82
00:03:24,229 --> 00:03:22,000
through robotics

83
00:03:27,190 --> 00:03:24,239
today exists

84
00:03:28,550 --> 00:03:27,200
and by use of the space station external

85
00:03:30,470 --> 00:03:28,560
platform

86
00:03:33,190 --> 00:03:30,480
we can in fact

87
00:03:35,350 --> 00:03:33,200
eliminate or reduce the risks

88
00:03:37,670 --> 00:03:35,360

of doing those kinds of tasks

89

00:03:39,670 --> 00:03:37,680

robotically in space

90

00:03:41,030 --> 00:03:39,680

and so with that let me turn it over to

91

00:03:42,710 --> 00:03:41,040

ben

92

00:03:44,830 --> 00:03:42,720

and oh excuse me

93

00:03:47,270 --> 00:03:44,840

matt it's all

94

00:03:49,509 --> 00:03:47,280

yours you very much um the canadian

95

00:03:52,149 --> 00:03:49,519

space agency is very pleased to be

96

00:03:54,229 --> 00:03:52,159

collaborating with nasa on this on the

97

00:03:55,110 --> 00:03:54,239

robotics refueling mission

98

00:03:57,110 --> 00:03:55,120

um

99

00:03:58,710 --> 00:03:57,120

we're quite looking forward to to this

100

00:04:01,750 --> 00:03:58,720

demonstration that will show that that

101
00:04:04,470 --> 00:04:01,760
space robots can use special tools and

102
00:04:06,710 --> 00:04:04,480
unique maneuvers in order to

103
00:04:08,390 --> 00:04:06,720
to service satellites even to the extent

104
00:04:11,110 --> 00:04:08,400
of refueling them

105
00:04:12,869 --> 00:04:11,120
and as was pointed out this this mission

106
00:04:14,710 --> 00:04:12,879
will be using the canadian build dexter

107
00:04:16,390 --> 00:04:14,720
which is a two-armed robot which was

108
00:04:17,590 --> 00:04:16,400
designed for the the space station's

109
00:04:19,509 --> 00:04:17,600
maintenance

110
00:04:21,349 --> 00:04:19,519
but this will be the first time for

111
00:04:22,629 --> 00:04:21,359
dexter that that dexter will be involved

112
00:04:24,950 --> 00:04:22,639
in such a research and development

113
00:04:26,310 --> 00:04:24,960

project as opposed to the routine

114

00:04:28,310 --> 00:04:26,320

maintenance

115

00:04:29,909 --> 00:04:28,320

and logistics on board the international

116

00:04:32,070 --> 00:04:29,919

space station

117

00:04:33,350 --> 00:04:32,080

so in canada we're we're quite proud of

118

00:04:34,710 --> 00:04:33,360

our our legacy in the field of space

119

00:04:35,990 --> 00:04:34,720

robotics

120

00:04:37,350 --> 00:04:36,000

if we look at the canadarm which has

121

00:04:38,550 --> 00:04:37,360

been on the space shuttle for the last

122

00:04:40,310 --> 00:04:38,560

30 years

123

00:04:41,590 --> 00:04:40,320

we alluded to early

124

00:04:43,270 --> 00:04:41,600

satellite servicing missions for

125

00:04:44,950 --> 00:04:43,280

instance the hubble space telescope

126
00:04:46,550 --> 00:04:44,960
servicing missions where the shuttle

127
00:04:50,310 --> 00:04:46,560
astronauts used

128
00:04:51,830 --> 00:04:50,320
the count arm to to catch and retrieve

129
00:04:53,110 --> 00:04:51,840
satellites to be repaired before

130
00:04:54,070 --> 00:04:53,120
releasing them

131
00:04:56,070 --> 00:04:54,080
so

132
00:04:57,830 --> 00:04:56,080
really that we had a lot of success with

133
00:05:00,230 --> 00:04:57,840
this and if you look more recently we've

134
00:05:01,430 --> 00:05:00,240
celebrated 10 years of canadarm2

135
00:05:03,510 --> 00:05:01,440
operations

136
00:05:06,790 --> 00:05:03,520
onboard the space station and this

137
00:05:09,029 --> 00:05:06,800
anniversary also marked the decade of of

138
00:05:10,950 --> 00:05:09,039

of intense collaboration between nasa

139

00:05:12,790 --> 00:05:10,960

and the canadian space agency

140

00:05:14,950 --> 00:05:12,800

as our respective teams of engineers

141

00:05:17,350 --> 00:05:14,960

have been working very closely together

142

00:05:18,710 --> 00:05:17,360

in the preparation and execution of

143

00:05:20,870 --> 00:05:18,720

day-to-day

144

00:05:24,150 --> 00:05:20,880

robotics operations and now if you look

145

00:05:26,629 --> 00:05:24,160

with dexter more recently even more

146

00:05:29,189 --> 00:05:26,639

dexter has been used recently for to

147

00:05:30,710 --> 00:05:29,199

offload the kunatori japanese resupply

148

00:05:32,950 --> 00:05:30,720

vehicle

149

00:05:34,550 --> 00:05:32,960

later on this summer it will be used in

150

00:05:37,029 --> 00:05:34,560

order to

151
00:05:39,189 --> 00:05:37,039
to replace a remote power controller

152
00:05:41,110 --> 00:05:39,199
module on board the space station

153
00:05:42,950 --> 00:05:41,120
so you can see that

154
00:05:44,870 --> 00:05:42,960
the robotics refueling mission is really

155
00:05:46,710 --> 00:05:44,880
falls well in line with with canada's

156
00:05:48,550 --> 00:05:46,720
own

157
00:05:49,909 --> 00:05:48,560
efforts in order to advance the field of

158
00:05:52,070 --> 00:05:49,919
space robotics

159
00:05:53,590 --> 00:05:52,080
um and and falls in line also with our

160
00:05:55,909 --> 00:05:53,600
the development of our and next

161
00:05:57,590 --> 00:05:55,919
generation canadarm project

162
00:05:58,790 --> 00:05:57,600
and um

163
00:06:00,790 --> 00:05:58,800

basically uh

164

00:06:02,950 --> 00:06:00,800

one one key difference though is that so

165

00:06:05,430 --> 00:06:02,960

far dexter has been used primarily in

166

00:06:07,990 --> 00:06:05,440

order to maintain uh devices that have

167

00:06:10,230 --> 00:06:08,000

been designed for robotic manipulation

168

00:06:12,150 --> 00:06:10,240

so we're quite looking forward to see

169

00:06:13,430 --> 00:06:12,160

how dexter will perform with those new

170

00:06:14,710 --> 00:06:13,440

tools

171

00:06:16,390 --> 00:06:14,720

because if you look at the tasks

172

00:06:18,070 --> 00:06:16,400

involved which are

173

00:06:19,670 --> 00:06:18,080

you know removing caps

174

00:06:21,590 --> 00:06:19,680

cutting through the exterior of a simula

175

00:06:23,110 --> 00:06:21,600

as the simulated exterior of a satellite

176

00:06:25,670 --> 00:06:23,120

or

177

00:06:28,469 --> 00:06:25,680

connecting a hose to a fuel valve

178

00:06:29,430 --> 00:06:28,479

those are all tasks which will

179

00:06:31,590 --> 00:06:29,440

you know

180

00:06:33,430 --> 00:06:31,600

present unprecedented demands on

181

00:06:36,309 --> 00:06:33,440

dexter's sense of touch

182

00:06:37,909 --> 00:06:36,319

and and find emotion so we're we're

183

00:06:41,110 --> 00:06:37,919

quite looking forward to

184

00:06:43,270 --> 00:06:41,120

to executing those tasks and seeing um

185

00:06:44,710 --> 00:06:43,280

basically how we can work together share

186

00:06:46,710 --> 00:06:44,720

our expertise

187

00:06:48,950 --> 00:06:46,720

as we tackle those those

188

00:06:51,029 --> 00:06:48,960

well these these new operations thank

189

00:06:52,309 --> 00:06:51,039

you

190

00:06:54,230 --> 00:06:52,319

all right so now we'll go to ben and

191

00:06:56,710 --> 00:06:54,240

hill give us a demonstration on just

192

00:06:58,150 --> 00:06:56,720

what the rrm mission will look like

193

00:07:01,830 --> 00:06:58,160

thank you d wayne

194

00:07:03,909 --> 00:07:01,840

thank you sepi and and matt

195

00:07:05,670 --> 00:07:03,919

name is ben reed i am the deputy project

196

00:07:07,430 --> 00:07:05,680

manager of the satellite servicing

197

00:07:09,749 --> 00:07:07,440

capabilities office

198

00:07:11,749 --> 00:07:09,759

so you heard both sepi and matt talk

199

00:07:12,950 --> 00:07:11,759

about different satellite servicing

200

00:07:14,830 --> 00:07:12,960

capabilities

201
00:07:16,950 --> 00:07:14,840
i like to think of it as a three-legged

202
00:07:19,029 --> 00:07:16,960
stool the first leg of satellite

203
00:07:21,189 --> 00:07:19,039
servicing is repair

204
00:07:22,710 --> 00:07:21,199
and refueling so i'm going to talk a lot

205
00:07:23,830 --> 00:07:22,720
about repair and refueling in just a

206
00:07:26,309 --> 00:07:23,840
minute here

207
00:07:27,589 --> 00:07:26,319
the second leg is in-orbit construction

208
00:07:29,350 --> 00:07:27,599
you have something that's too big to fit

209
00:07:31,270 --> 00:07:29,360
in a single rocket when you fly up two

210
00:07:33,749 --> 00:07:31,280
halves you join in space that's another

211
00:07:36,629 --> 00:07:33,759
capability that satellite servicing

212
00:07:39,029 --> 00:07:36,639
brings to the agency and to the to the

213
00:07:42,629 --> 00:07:39,039

international space community

214

00:07:45,350 --> 00:07:42,639

the third is active orbital debris

215

00:07:47,029 --> 00:07:45,360

uh removal to be able to the ability to

216

00:07:48,550 --> 00:07:47,039

go up and grapple something that wasn't

217

00:07:50,550 --> 00:07:48,560

designed to be grappled and then do

218

00:07:52,950 --> 00:07:50,560

something with it push it up push it

219

00:07:54,950 --> 00:07:52,960

down dispose of it somehow so those are

220

00:07:57,510 --> 00:07:54,960

the three main

221

00:07:59,270 --> 00:07:57,520

legs of the satellite servicing stool so

222

00:08:01,430 --> 00:07:59,280

i'm going to talk a lot about repair and

223

00:08:03,990 --> 00:08:01,440

refueling

224

00:08:05,270 --> 00:08:04,000

so i've got four wonderful kids at home

225

00:08:06,710 --> 00:08:05,280

they're a little bit older now but when

226

00:08:08,550 --> 00:08:06,720

they were small

227

00:08:11,350 --> 00:08:08,560

i used to buy them toys obviously one of

228

00:08:13,189 --> 00:08:11,360

which was a fisher-price workbench right

229

00:08:14,710 --> 00:08:13,199

what comes in the box when you get it

230

00:08:16,790 --> 00:08:14,720

it's a little tool bench with some

231

00:08:19,110 --> 00:08:16,800

little plastic nails and a plastic

232

00:08:21,589 --> 00:08:19,120

hammer so the nails is what the hammer

233

00:08:23,430 --> 00:08:21,599

hits you don't get a little arm inside

234

00:08:25,670 --> 00:08:23,440

there to control it that's what the kid

235

00:08:27,749 --> 00:08:25,680

provides the kid picks up the tool hits

236

00:08:30,390 --> 00:08:27,759

the little plastic nails well that's

237

00:08:34,389 --> 00:08:30,400

exactly what we have here on our high

238

00:08:37,750 --> 00:08:34,399

fidelity mechanical simulator that we

239

00:08:41,909 --> 00:08:37,760

at goddard built so to help us with the

240

00:08:44,949 --> 00:08:41,919

rrm module which is obviously on um in

241

00:08:46,710 --> 00:08:44,959

the sts-135 right now ready for launch

242

00:08:49,350 --> 00:08:46,720

and just let me pause for a moment to

243

00:08:51,590 --> 00:08:49,360

say how humbled and proud we are to be

244

00:08:53,590 --> 00:08:51,600

part of sts-135 could not be more

245

00:08:55,110 --> 00:08:53,600

excited to be here

246

00:08:57,590 --> 00:08:55,120

for this launch

247

00:08:59,110 --> 00:08:57,600

so here we have our fisher-price toy box

248

00:09:01,110 --> 00:08:59,120

at the risk of being misquoted i'm going

249

00:09:03,190 --> 00:09:01,120

to try to stick with that analogy

250

00:09:04,790 --> 00:09:03,200

so

251
00:09:07,110 --> 00:09:04,800
what are the nails what are the things

252
00:09:09,269 --> 00:09:07,120
we're going to work on well those are

253
00:09:11,990 --> 00:09:09,279
legacy satellite interfaces interfaces

254
00:09:13,190 --> 00:09:12,000
that were not designed to be serviced in

255
00:09:16,070 --> 00:09:13,200
orbit

256
00:09:18,310 --> 00:09:16,080
primarily i will talk about a fill and

257
00:09:19,829 --> 00:09:18,320
drain valve so

258
00:09:22,470 --> 00:09:19,839
satellites

259
00:09:24,070 --> 00:09:22,480
that are built around the nation

260
00:09:26,150 --> 00:09:24,080
at goddard and many other places are

261
00:09:27,829 --> 00:09:26,160
sent to kennedy for processing they are

262
00:09:29,829 --> 00:09:27,839
empty they have no propellant inside

263
00:09:31,350 --> 00:09:29,839

when they arrive they get to the launch

264

00:09:33,269 --> 00:09:31,360

pad and now they're ready to receive

265

00:09:35,269 --> 00:09:33,279

their propellant right very hazardous so

266

00:09:36,870 --> 00:09:35,279

we do it late in the flow

267

00:09:38,790 --> 00:09:36,880

so this is what a fill and drain valve

268

00:09:40,630 --> 00:09:38,800

looks like right you see a quarter inch

269

00:09:42,230 --> 00:09:40,640

diameter hole here so somehow we're

270

00:09:43,829 --> 00:09:42,240

going to get the fuel in through this

271

00:09:45,910 --> 00:09:43,839

quarter inch diameter hole into the

272

00:09:48,949 --> 00:09:45,920

satellite so when it gets in orbit it's

273

00:09:51,829 --> 00:09:48,959

got propellant so they thread on to this

274

00:09:53,070 --> 00:09:51,839

last male threads here they pump in the

275

00:09:56,550 --> 00:09:53,080

hydrazine

276

00:09:58,550 --> 00:09:56,560

tetroxide

277

00:10:00,949 --> 00:09:58,560

they then rotate this silver nut here

278

00:10:02,949 --> 00:10:00,959

and that closes off an internal seal now

279

00:10:04,470 --> 00:10:02,959

the fluid is contained inside the

280

00:10:06,470 --> 00:10:04,480

satellite but

281

00:10:08,470 --> 00:10:06,480

it's so hazardous they need extra

282

00:10:11,110 --> 00:10:08,480

precaution right if that seal were to

283

00:10:13,430 --> 00:10:11,120

fail and to propel them or to leak out

284

00:10:16,150 --> 00:10:13,440

very bad for the humans in the area and

285

00:10:18,550 --> 00:10:16,160

we like to be safe so they put on

286

00:10:21,509 --> 00:10:18,560

a secondary cap that provides additional

287

00:10:23,030 --> 00:10:21,519

safety and it is cleverly called a

288

00:10:23,990 --> 00:10:23,040

safety cap

289

00:10:26,389 --> 00:10:24,000

so

290

00:10:28,069 --> 00:10:26,399

safety cap goes on next now we've got

291

00:10:30,470 --> 00:10:28,079

two seals the internal seal and the

292

00:10:32,630 --> 00:10:30,480

safety cap

293

00:10:35,110 --> 00:10:32,640

now they put on safety wire to prevent

294

00:10:37,509 --> 00:10:35,120

the actuation nut or the safety cap from

295

00:10:40,069 --> 00:10:37,519

inadvertently backing off during launch

296

00:10:41,750 --> 00:10:40,079

loads or ground processing loads they

297

00:10:43,829 --> 00:10:41,760

put safety wire

298

00:10:47,190 --> 00:10:43,839

to hold it in place and i'll show you

299

00:10:49,750 --> 00:10:47,200

safety wire on the module in a moment

300

00:10:51,509 --> 00:10:49,760

finally they put on a tertiary cap the

301
00:10:52,790 --> 00:10:51,519
tertiary cap goes over the whole

302
00:10:54,790 --> 00:10:52,800
assembly

303
00:10:56,630 --> 00:10:54,800
and it is safety wired shut so now we

304
00:10:58,230 --> 00:10:56,640
have two fault tolerance two of the

305
00:11:00,630 --> 00:10:58,240
seals can fail we've got a third one

306
00:11:03,670 --> 00:11:00,640
that will keep the hazardous fuel inside

307
00:11:05,269 --> 00:11:03,680
the spacecraft not where the humans are

308
00:11:06,870 --> 00:11:05,279
so if we're going to undo this

309
00:11:08,550 --> 00:11:06,880
robotically we've got to reverse those

310
00:11:09,990 --> 00:11:08,560
steps so

311
00:11:12,550 --> 00:11:10,000
safety wire is the first thing we need

312
00:11:16,389 --> 00:11:12,560
to tackle so take a guess what we call

313
00:11:18,710 --> 00:11:16,399

the tool that we use to cut wire

314

00:11:20,710 --> 00:11:18,720

the wire cutter tool exactly right

315

00:11:22,630 --> 00:11:20,720

so we have a wire cutter tool

316

00:11:24,470 --> 00:11:22,640

and rather than pulling out of the bays

317

00:11:25,990 --> 00:11:24,480

where it's stored for launch i'll show

318

00:11:27,110 --> 00:11:26,000

you this one so here's our wire cutter

319

00:11:30,870 --> 00:11:27,120

tool

320

00:11:32,310 --> 00:11:30,880

has at the tip of it

321

00:11:34,389 --> 00:11:32,320

a hook it's kind of hard to see it's on

322

00:11:37,110 --> 00:11:34,399

the back side that we use to hook around

323

00:11:38,150 --> 00:11:37,120

a piece of wire we then use the dexter

324

00:11:39,750 --> 00:11:38,160

robot

325

00:11:42,550 --> 00:11:39,760

by our good friends at the canadian

326
00:11:45,190 --> 00:11:42,560
space agency which is holding our tool

327
00:11:47,269 --> 00:11:45,200
to drive the torque or drive which

328
00:11:48,949 --> 00:11:47,279
activates a lead screw inside and it

329
00:11:51,030 --> 00:11:48,959
closes down a little blade which chops

330
00:11:53,030 --> 00:11:51,040
the wire in half so now we've just done

331
00:11:55,590 --> 00:11:53,040
our first robotic activity

332
00:11:57,590 --> 00:11:55,600
this robotic activity is controlled via

333
00:12:00,150 --> 00:11:57,600
our friends down in johnson space center

334
00:12:01,509 --> 00:12:00,160
a partner with us on the rrm mission

335
00:12:03,910 --> 00:12:01,519
they are flying the robot they are

336
00:12:05,750 --> 00:12:03,920
flying the dexter robot from the thicker

337
00:12:08,389 --> 00:12:05,760
one at mission control in houston so

338
00:12:11,509 --> 00:12:08,399

very tight collaboration with our robo

339

00:12:14,150 --> 00:12:11,519

friends in houston so we cut the wire

340

00:12:16,150 --> 00:12:14,160

and now we're ready to we put that tool

341

00:12:17,670 --> 00:12:16,160

away now we're ready to go after the

342

00:12:25,030 --> 00:12:17,680

tertiary cap

343

00:12:27,030 --> 00:12:25,040

that be the sole function of the tool

344

00:12:28,389 --> 00:12:27,040

we designed a tool that has multiple

345

00:12:30,790 --> 00:12:28,399

functions

346

00:12:32,389 --> 00:12:30,800

so we call it the multi-function tool

347

00:12:33,829 --> 00:12:32,399

so the multi-function tool will pick up

348

00:12:35,990 --> 00:12:33,839

one of four adapters and the four

349

00:12:38,150 --> 00:12:36,000

adapters are stored in these four

350

00:12:39,509 --> 00:12:38,160

receptacles you see on top of our

351
00:12:41,829 --> 00:12:39,519
mock-up here

352
00:12:44,069 --> 00:12:41,839
so we pick up the tertiary cap adapter

353
00:12:46,310 --> 00:12:44,079
out of this location

354
00:12:48,470 --> 00:12:46,320
it attaches to the end of the

355
00:12:49,269 --> 00:12:48,480
multi-function tool and now with that

356
00:12:53,430 --> 00:12:49,279
tool

357
00:12:54,710 --> 00:12:53,440
we engage the tertiary cap unscrew it

358
00:12:57,110 --> 00:12:54,720
take it off

359
00:12:59,910 --> 00:12:57,120
so that cap is then stowed

360
00:13:02,150 --> 00:12:59,920
in here and now we've exposed the two

361
00:13:04,389 --> 00:13:02,160
safety wires and the safety cap

362
00:13:06,069 --> 00:13:04,399
we picked the wire cutter tool back up

363
00:13:07,829 --> 00:13:06,079

we cut the two pieces of wire here just

364

00:13:08,949 --> 00:13:07,839

like we did the first one

365

00:13:11,269 --> 00:13:08,959

and

366

00:13:13,910 --> 00:13:11,279

we then use our safety cap tool

367

00:13:15,509 --> 00:13:13,920

and i will remove the safety cap tool

368

00:13:20,389 --> 00:13:15,519

just the way the dexter robot would do

369

00:13:23,590 --> 00:13:21,829

so

370

00:13:26,470 --> 00:13:23,600

this is how the safety cap tool is

371

00:13:27,590 --> 00:13:26,480

removed so here is our 18 pound safety

372

00:13:29,430 --> 00:13:27,600

cap tool

373

00:13:31,269 --> 00:13:29,440

it looks rather complex let me see if i

374

00:13:33,350 --> 00:13:31,279

can break it down a little bit simpler

375

00:13:35,190 --> 00:13:33,360

so the active part of the tool is right

376

00:13:37,430 --> 00:13:35,200

down the center the center shaft is

377

00:13:40,870 --> 00:13:37,440

where all the gears the mechanisms are

378

00:13:42,310 --> 00:13:40,880

that allow the dexter robot to actuate

379

00:13:45,189 --> 00:13:42,320

its torque or drive

380

00:13:48,069 --> 00:13:45,199

to engage the safety cap and unscrew it

381

00:13:50,150 --> 00:13:48,079

from the robot well the robo flyers as

382

00:13:51,350 --> 00:13:50,160

good as they are down in houston they

383

00:13:53,189 --> 00:13:51,360

have to be able to see what they're

384

00:13:55,829 --> 00:13:53,199

doing obviously so

385

00:13:58,470 --> 00:13:55,839

we have two integral cameras and their

386

00:13:59,350 --> 00:13:58,480

led lights which allow the robo flyer to

387

00:14:01,670 --> 00:13:59,360

see

388

00:14:02,629 --> 00:14:01,680

the business end of the tool

389

00:14:05,030 --> 00:14:02,639

so

390

00:14:07,750 --> 00:14:05,040

the safety cap tool then engages the

391

00:14:11,509 --> 00:14:07,760

safety cap removes it

392

00:14:14,470 --> 00:14:11,519

and that part of the job is done

393

00:14:17,030 --> 00:14:14,480

so now we have an exposed or

394

00:14:19,910 --> 00:14:17,040

naked fill and drain valve so the safety

395

00:14:21,590 --> 00:14:19,920

cap has now been removed

396

00:14:23,269 --> 00:14:21,600

leaving behind a fill and drain valve

397

00:14:25,110 --> 00:14:23,279

that looks like this so now we would

398

00:14:27,030 --> 00:14:25,120

need to

399

00:14:28,389 --> 00:14:27,040

do the robotic activity to attach to

400

00:14:30,949 --> 00:14:28,399

these male threads

401
00:14:32,790 --> 00:14:30,959
and transfer fluid into it just as a

402
00:14:34,550 --> 00:14:32,800
spacecraft in orbit would give the

403
00:14:36,150 --> 00:14:34,560
customer satellite

404
00:14:37,269 --> 00:14:36,160
more propellant

405
00:14:39,910 --> 00:14:37,279
so

406
00:14:41,430 --> 00:14:39,920
we use our final tool here our fourth

407
00:14:43,670 --> 00:14:41,440
tool

408
00:14:45,269 --> 00:14:43,680
and that is an embedded acronym

409
00:14:47,829 --> 00:14:45,279
it's the evr

410
00:14:50,470 --> 00:14:47,839
nozzle tool or ent

411
00:14:52,069 --> 00:14:50,480
so not an eva activity no astronauts

412
00:14:54,310 --> 00:14:52,079
involved with this demonstration it's

413
00:14:55,750 --> 00:14:54,320

all robotic so it's an evr

414

00:14:56,949 --> 00:14:55,760

nozzle tool

415

00:14:58,629 --> 00:14:56,959

and you can see what's different about

416

00:15:00,470 --> 00:14:58,639

this one right off the bat is that it

417

00:15:02,550 --> 00:15:00,480

has this hose connected to it well

418

00:15:04,790 --> 00:15:02,560

obviously we have to flow fluid somehow

419

00:15:07,509 --> 00:15:04,800

so we use that hose

420

00:15:10,069 --> 00:15:07,519

which after we thread on to the exposed

421

00:15:12,949 --> 00:15:10,079

threads here we're able to pump fluid

422

00:15:15,829 --> 00:15:12,959

through the ent and into an internal

423

00:15:18,310 --> 00:15:15,839

system we have a series of tanks valves

424

00:15:21,829 --> 00:15:18,320

latches inside

425

00:15:24,069 --> 00:15:21,839

the module that we command through elc

426

00:15:25,509 --> 00:15:24,079

via our other partner in this mission

427

00:15:28,230 --> 00:15:25,519

and that is the marshall space flight

428

00:15:31,430 --> 00:15:28,240

center we have been working very well uh

429

00:15:32,230 --> 00:15:31,440

with the command team down at marshall

430

00:15:44,230 --> 00:15:32,240

to

431

00:15:45,910 --> 00:15:44,240

about the the steps involved with

432

00:15:47,430 --> 00:15:45,920

robotic refueling

433

00:15:50,949 --> 00:15:47,440

we have a lot of other tasks we're going

434

00:15:52,550 --> 00:15:50,959

to do on this mission but refueling is

435

00:15:54,230 --> 00:15:52,560

one of them so

436

00:15:56,310 --> 00:15:54,240

i have a video now that i've gone into

437

00:15:58,710 --> 00:15:56,320

great detail and i'm sure have confused

438

00:15:59,749 --> 00:15:58,720

all of you if we could roll the video

439

00:16:01,590 --> 00:15:59,759

please

440

00:16:03,189 --> 00:16:01,600

and you'll be able to get

441

00:16:08,069 --> 00:16:03,199

an overview of what the mission is going

442

00:16:10,949 --> 00:16:09,269

okay

443

00:16:13,670 --> 00:16:10,959

so

444

00:16:16,150 --> 00:16:13,680

after launch on flight day five

445

00:16:18,629 --> 00:16:16,160

we will be picked up by the eva crew

446

00:16:22,550 --> 00:16:18,639

member the iss eva crew member and

447

00:16:24,230 --> 00:16:22,560

transfer it over to the eotp platform

448

00:16:28,150 --> 00:16:24,240

a few weeks after that we'll be moved

449

00:16:30,150 --> 00:16:28,160

from the eotp platform to elc 4

450

00:16:31,590 --> 00:16:30,160

which is at the far right side of the

451
00:16:34,310 --> 00:16:31,600
video screen

452
00:16:35,509 --> 00:16:34,320
once we are located on elc 4

453
00:16:37,110 --> 00:16:35,519
then the

454
00:16:38,949 --> 00:16:37,120
ssrms

455
00:16:40,629 --> 00:16:38,959
picking up the two arm dexter will be

456
00:16:41,430 --> 00:16:40,639
moved over just as you see in the video

457
00:16:43,350 --> 00:16:41,440
now

458
00:16:45,670 --> 00:16:43,360
and it will begin the operation so i've

459
00:16:46,710 --> 00:16:45,680
talked about the four tools that will be

460
00:16:48,870 --> 00:16:46,720
picked up

461
00:16:49,670 --> 00:16:48,880
here you can see in the video

462
00:16:53,269 --> 00:16:49,680
that

463
00:16:55,030 --> 00:16:53,279

one of dexter's arms is going in

464

00:16:58,069 --> 00:16:55,040
and making contact

465

00:17:00,790 --> 00:16:58,079
so this shows you from a big picture how

466

00:17:03,670 --> 00:17:00,800
at the end of a 55 foot arm the two arm

467

00:17:06,710 --> 00:17:03,680
dexter will be doing the operations

468

00:17:09,909 --> 00:17:06,720
so here you see a split screen

469

00:17:12,150 --> 00:17:09,919
the image in the upper left is the view

470

00:17:13,990 --> 00:17:12,160
that the robo flyer will get right these

471

00:17:16,230 --> 00:17:14,000
are from the the camera is located on

472

00:17:18,069 --> 00:17:16,240
top you see the god's eye view in the

473

00:17:20,390 --> 00:17:18,079
center of the screen but you see the

474

00:17:22,549 --> 00:17:20,400
tool camera view so that's the view that

475

00:17:23,270 --> 00:17:22,559
the robo flyer gets when the operations

476

00:17:25,350 --> 00:17:23,280

are

477

00:17:27,669 --> 00:17:25,360

being conducted so you can see that

478

00:17:30,549 --> 00:17:27,679

safety wire is mighty hard to see so it

479

00:17:32,390 --> 00:17:30,559

took a tremendous amount of coordination

480

00:17:35,669 --> 00:17:32,400

with our tool development team

481

00:17:38,789 --> 00:17:35,679

at goddard the robo flyers at johnson

482

00:17:40,470 --> 00:17:38,799

the operations folks up at csa who are

483

00:17:42,950 --> 00:17:40,480

building um

484

00:17:44,710 --> 00:17:42,960

the re configuration files for the robot

485

00:17:46,710 --> 00:17:44,720

for this so tremendous amount of

486

00:17:48,789 --> 00:17:46,720

coordination was required

487

00:17:50,310 --> 00:17:48,799

so now you see

488

00:17:52,390 --> 00:17:50,320

a close-up view

489

00:17:53,110 --> 00:17:52,400

of the very end of dexter's arm picking

490

00:17:55,350 --> 00:17:53,120

up

491

00:17:58,950 --> 00:17:55,360

the multi-function tool

492

00:18:00,390 --> 00:17:58,960

quiz anyone paying attention what does

493

00:18:02,870 --> 00:18:00,400

it need to pick up to remove the

494

00:18:06,710 --> 00:18:02,880

tertiary cap

495

00:18:09,669 --> 00:18:06,720

people in the audience that are on my

496

00:18:10,950 --> 00:18:09,679

team you guys should know the answer

497

00:18:13,590 --> 00:18:10,960

all right so here we have the tertiary

498

00:18:15,909 --> 00:18:13,600

cap adapter and it is going to go after

499

00:18:18,230 --> 00:18:15,919

you got it the tertiary cap again the

500

00:18:20,150 --> 00:18:18,240

split screen the window and window

501
00:18:23,430 --> 00:18:20,160
that is the actual laboratory footage

502
00:18:25,110 --> 00:18:23,440
sped up tremendously i might add

503
00:18:26,710 --> 00:18:25,120
the removing of the tertiary cap so

504
00:18:29,350 --> 00:18:26,720
we've done these operations on the

505
00:18:31,590 --> 00:18:29,360
ground in the lab many many times what

506
00:18:35,590 --> 00:18:31,600
we haven't done is these operations in

507
00:18:36,870 --> 00:18:35,600
orbit so that's what rrm is it's the on

508
00:18:39,430 --> 00:18:36,880
orbit

509
00:18:42,950 --> 00:18:39,440
the zero-g demonstration

510
00:18:44,390 --> 00:18:42,960
of robotic refueling of legacy

511
00:18:46,150 --> 00:18:44,400
interfaces

512
00:18:47,590 --> 00:18:46,160
for the first time

513
00:18:48,950 --> 00:18:47,600

again we've done it many times on the

514

00:18:50,390 --> 00:18:48,960

ground but we've never been able we've

515

00:18:51,669 --> 00:18:50,400

never done it in orbit so that's what

516

00:18:54,950 --> 00:18:51,679

rrm we

517

00:18:56,950 --> 00:18:54,960

anticipate it enabling future missions

518

00:18:59,750 --> 00:18:56,960

future capabilities for the

519

00:19:01,430 --> 00:18:59,760

international aerospace community

520

00:19:03,350 --> 00:19:01,440

thank you very much

521

00:19:04,870 --> 00:19:03,360

all right so now we'll open up for

522

00:19:06,549 --> 00:19:04,880

questions

523

00:19:08,150 --> 00:19:06,559

i'll ask that you wait for the

524

00:19:09,669 --> 00:19:08,160

microphone first

525

00:19:10,470 --> 00:19:09,679

when we get there please state your full

526

00:19:12,310 --> 00:19:10,480

name

527

00:19:14,150 --> 00:19:12,320

and your affiliation

528

00:19:17,669 --> 00:19:14,160

so we'll begin with the gentleman

529

00:19:20,789 --> 00:19:19,590

uh jim siegel celebration independent

530

00:19:22,549 --> 00:19:20,799

newspaper

531

00:19:23,909 --> 00:19:22,559

um i may be a little slow here i just

532

00:19:25,590 --> 00:19:23,919

kind of wanted to make sure that i

533

00:19:27,830 --> 00:19:25,600

understood what you were talking about

534

00:19:29,590 --> 00:19:27,840

so this this module

535

00:19:31,510 --> 00:19:29,600

is going to be attached to the outside

536

00:19:33,669 --> 00:19:31,520

of the international space station

537

00:19:35,350 --> 00:19:33,679

correct correct and it's going to stay

538

00:19:37,350 --> 00:19:35,360

there indefinitely is that correct it's

539

00:19:39,430 --> 00:19:37,360

not coming back or land operation just

540

00:19:42,230 --> 00:19:39,440

two years of operations afterward that

541

00:19:43,669 --> 00:19:42,240

is the current plan okay and then the

542

00:19:48,549 --> 00:19:43,679

arm

543

00:19:50,950 --> 00:19:48,559

would uh capture and retrieve a

544

00:19:53,110 --> 00:19:50,960

satellite

545

00:19:56,630 --> 00:19:53,120

correct let me correct you there okay so

546

00:19:58,310 --> 00:19:56,640

rather than bringing a satellite to iss

547

00:20:00,150 --> 00:19:58,320

that would be rather challenging to do

548

00:20:01,909 --> 00:20:00,160

from an orbit dynamics point of view and

549

00:20:04,470 --> 00:20:01,919

from a safety point of view

550

00:20:06,870 --> 00:20:04,480

so rather than bringing a customer

551
00:20:09,190 --> 00:20:06,880
satellite to iss first we need to

552
00:20:10,870 --> 00:20:09,200
demonstrate the technology on mock

553
00:20:12,789 --> 00:20:10,880
satellite interfaces

554
00:20:15,270 --> 00:20:12,799
so what you see here

555
00:20:18,549 --> 00:20:15,280
is a fill and drain valve that is

556
00:20:20,630 --> 00:20:18,559
exactly like it would be on

557
00:20:23,590 --> 00:20:20,640
a real satellite in orbit so we are

558
00:20:25,590 --> 00:20:23,600
going to demonstrate the capability here

559
00:20:27,590 --> 00:20:25,600
before we do it for real on a satellite

560
00:20:30,149 --> 00:20:27,600
so i've seen in the press i've seen in

561
00:20:33,190 --> 00:20:30,159
the press it is easy to talk about rrm

562
00:20:36,070 --> 00:20:33,200
as a gas station in space

563
00:20:38,390 --> 00:20:36,080

that is the next mission this mission is

564

00:20:40,549 --> 00:20:38,400

to show that the technology exists today

565

00:20:42,710 --> 00:20:40,559

to show that we have the the capability

566

00:20:44,470 --> 00:20:42,720

today rather than to start refueling

567

00:20:46,149 --> 00:20:44,480

satellites

568

00:20:48,710 --> 00:20:46,159

a week from now when we're in orbit okay

569

00:20:51,350 --> 00:20:48,720

so this demonstration module is going to

570

00:20:53,190 --> 00:20:51,360

stay attached to the iss for two years

571

00:20:55,350 --> 00:20:53,200

yes and it's going to be

572

00:20:57,909 --> 00:20:55,360

only demonstrating it's not going to be

573

00:21:00,310 --> 00:20:57,919

servicing any other i went into great

574

00:21:02,149 --> 00:21:00,320

detail about the refueling part of it we

575

00:21:04,149 --> 00:21:02,159

have five major tasks that we are going

576
00:21:06,549 --> 00:21:04,159
to do with rrm but for the sake of time

577
00:21:09,350 --> 00:21:06,559
i focus just on refueling we have a lot

578
00:21:11,830 --> 00:21:09,360
of other interfaces you can see

579
00:21:13,590 --> 00:21:11,840
she's a pretty porcupine is she not

580
00:21:15,270 --> 00:21:13,600
well

581
00:21:16,630 --> 00:21:15,280
there we've got lots of other tools

582
00:21:18,230 --> 00:21:16,640
we've got lots of other adapters we've

583
00:21:21,270 --> 00:21:18,240
got lots of other legacy satellite

584
00:21:22,870 --> 00:21:21,280
interfaces that we're going to practice

585
00:21:25,590 --> 00:21:22,880
limited repair

586
00:21:27,669 --> 00:21:25,600
and other servicing tasks on it so i've

587
00:21:29,270 --> 00:21:27,679
just talked about refueling today so

588
00:21:31,430 --> 00:21:29,280

it's going to take us two years to make

589

00:21:32,390 --> 00:21:31,440

it through the entire gamut of planned

590

00:21:34,230 --> 00:21:32,400

tasks

591

00:21:35,190 --> 00:21:34,240

and then there is is there a timeline

592

00:21:38,070 --> 00:21:35,200

for

593

00:21:40,149 --> 00:21:38,080

when something like this an operational

594

00:21:41,909 --> 00:21:40,159

phase ii whatever device

595

00:21:44,549 --> 00:21:41,919

would be attached to the space station

596

00:21:46,470 --> 00:21:44,559

and the idea is eventually phase two

597

00:21:48,390 --> 00:21:46,480

phase three whatever to capture

598

00:21:51,350 --> 00:21:48,400

satellites and bring them in and the

599

00:21:54,470 --> 00:21:51,360

substance the subsequent phase would be

600

00:21:57,029 --> 00:21:54,480

to build a standalone robotic servicing

601
00:22:01,350 --> 00:21:57,039
spacecraft to go do real satellites in

602
00:22:02,950 --> 00:22:01,360
orbit orbit dynamics being what they are

603
00:22:05,190 --> 00:22:02,960
if you're not near space station it

604
00:22:06,710 --> 00:22:05,200
takes a tremendous amount of fuel to get

605
00:22:09,029 --> 00:22:06,720
there so

606
00:22:11,190 --> 00:22:09,039
or somebody to need service in orbit you

607
00:22:13,350 --> 00:22:11,200
send a tow truck to them or

608
00:22:15,110 --> 00:22:13,360
geosynchronous orbit as my boss frank

609
00:22:17,029 --> 00:22:15,120
seppolina mentioned there's well over

610
00:22:18,230 --> 00:22:17,039
400 satellites they're all at the same

611
00:22:20,390 --> 00:22:18,240
altitude

612
00:22:21,510 --> 00:22:20,400
almost the same angle and going the same

613
00:22:23,510 --> 00:22:21,520

direction

614

00:22:26,230 --> 00:22:23,520

so geosynchronous orbit seems like a

615

00:22:28,070 --> 00:22:26,240

very logical place to launch the first

616

00:22:28,950 --> 00:22:28,080

servicing mission right you're not going

617

00:22:33,590 --> 00:22:28,960

to

618

00:22:34,870 --> 00:22:33,600

come by right

619

00:22:36,950 --> 00:22:34,880

you're going to put it strategically

620

00:22:39,510 --> 00:22:36,960

where you can get to a lot of customers

621

00:22:41,830 --> 00:22:39,520

quickly so were i to be designing a

622

00:22:43,029 --> 00:22:41,840

mission to go and service satellites to

623

00:22:45,110 --> 00:22:43,039

space i'd want to go where there's a lot

624

00:22:46,950 --> 00:22:45,120

of customers going the same direction to

625

00:22:48,390 --> 00:22:46,960

minimize the amount of fuel to get to

626
00:22:50,710 --> 00:22:48,400
them and that would be geosynchronous

627
00:22:52,950 --> 00:22:50,720
orbit

628
00:22:54,630 --> 00:22:52,960
all right so gentlemen right here the

629
00:22:57,029 --> 00:22:54,640
front

630
00:22:58,870 --> 00:22:57,039
hi ken kramer space flight magazine um

631
00:23:01,110 --> 00:22:58,880
question about the canadian involvement

632
00:23:03,270 --> 00:23:01,120
i was wondering um when when dexter was

633
00:23:05,590 --> 00:23:03,280
uh was launched and

634
00:23:07,909 --> 00:23:05,600
conceptualized was was this

635
00:23:10,870 --> 00:23:07,919
rrm on the plate or was this kind of

636
00:23:12,390 --> 00:23:10,880
added afterwards thanks

637
00:23:14,950 --> 00:23:12,400
that's a very good question no it was

638
00:23:17,110 --> 00:23:14,960

not so basically dexter's main mission

639

00:23:18,549 --> 00:23:17,120

on board the station is to

640

00:23:20,310 --> 00:23:18,559

perform maintenance and logistics

641

00:23:21,830 --> 00:23:20,320

operations for

642

00:23:23,909 --> 00:23:21,840

components that have been designed to be

643

00:23:27,510 --> 00:23:23,919

handled robotically and clearly one of

644

00:23:28,630 --> 00:23:27,520

the purposes of this demonstration is to

645

00:23:30,470 --> 00:23:28,640

demonstrate that you can actually

646

00:23:33,110 --> 00:23:30,480

interact with components that have not

647

00:23:35,110 --> 00:23:33,120

been designed for robotic manipulation

648

00:23:36,870 --> 00:23:35,120

so i think we had enough flexibility in

649

00:23:38,950 --> 00:23:36,880

the system

650

00:23:40,870 --> 00:23:38,960

the ability to interface with tools to

651
00:23:43,750 --> 00:23:40,880
upgrade software to

652
00:23:45,750 --> 00:23:43,760
optimize its performance using special

653
00:23:48,230 --> 00:23:45,760
specialized robotics

654
00:23:49,990 --> 00:23:48,240
configuration files that allows us to do

655
00:23:51,669 --> 00:23:50,000
that but definitely one of the objective

656
00:23:53,909 --> 00:23:51,679
for us of this

657
00:23:55,750 --> 00:23:53,919
of this particular demonstration is to

658
00:23:58,870 --> 00:23:55,760
see just how far we can push dexter and

659
00:24:01,350 --> 00:23:58,880
accomplish those those exciting tasks

660
00:24:04,390 --> 00:24:01,360
that must be very exciting

661
00:24:07,190 --> 00:24:04,400
a very exciting uh uh avenue for you are

662
00:24:08,630 --> 00:24:07,200
there any other um dexter um

663
00:24:10,549 --> 00:24:08,640

operations coming up that are new that

664

00:24:12,789 --> 00:24:10,559

you could tell us about

665

00:24:15,029 --> 00:24:12,799

well dexter really has been in full

666

00:24:17,990 --> 00:24:15,039

operation since 2010 it arrived in 2008

667

00:24:20,230 --> 00:24:18,000

but we really started in earnest to to

668

00:24:20,950 --> 00:24:20,240

operate it for for instance to offload

669

00:24:25,269 --> 00:24:20,960

the

670

00:24:28,230 --> 00:24:25,279

next year

671

00:24:29,830 --> 00:24:28,240

sorry later on this summer we will be

672

00:24:32,390 --> 00:24:29,840

changing out a remote power controller

673

00:24:34,950 --> 00:24:32,400

module if you recall last year we had

674

00:24:36,950 --> 00:24:34,960

we had attempted to do so but the

675

00:24:39,590 --> 00:24:36,960

the module did not meet exactly all the

676

00:24:41,990 --> 00:24:39,600

the required robotics requirements

677

00:24:43,830 --> 00:24:42,000

and uh but we were able to perform more

678

00:24:46,549 --> 00:24:43,840

analysis and now we're we're going to

679

00:24:49,669 --> 00:24:46,559

continue doing so so in a way

680

00:24:52,390 --> 00:24:49,679

um all new operations every every new on

681

00:24:54,789 --> 00:24:52,400

orbit replaceable unit we we we change

682

00:24:56,230 --> 00:24:54,799

out brings us a wealth of additional

683

00:24:58,070 --> 00:24:56,240

knowledge for us

684

00:25:00,230 --> 00:24:58,080

if you look just at the operation of the

685

00:25:01,990 --> 00:25:00,240

of dexter it originally it was uh

686

00:25:03,590 --> 00:25:02,000

conceived as purely operated by

687

00:25:05,510 --> 00:25:03,600

astronauts onboard the station and now

688

00:25:07,669 --> 00:25:05,520

its primary mode of operation has

689

00:25:09,669 --> 00:25:07,679

transitioned over to ground operators so

690

00:25:11,350 --> 00:25:09,679

it's a very exciting time for all

691

00:25:15,190 --> 00:25:11,360

involved

692

00:25:18,310 --> 00:25:15,200

all right take this gentleman right here

693

00:25:20,390 --> 00:25:18,320

yeah hi mike wahl from space.com um so

694

00:25:21,510 --> 00:25:20,400

yeah so this is actually already i mean

695

00:25:23,510 --> 00:25:21,520

you've already shown this can work in

696

00:25:25,029 --> 00:25:23,520

the lab i was just wondering i mean what

697

00:25:26,390 --> 00:25:25,039

are your your kind of thoughts about

698

00:25:28,230 --> 00:25:26,400

what the main challenges are going to be

699

00:25:29,190 --> 00:25:28,240

in space what are what are some of the

700

00:25:31,110 --> 00:25:29,200

biggest hurdles that you're going to

701
00:25:33,029 --> 00:25:31,120
have to overcome and i mean how much

702
00:25:35,909 --> 00:25:33,039
more difficult is that going to be than

703
00:25:37,510 --> 00:25:35,919
what you've already seen it do

704
00:25:39,190 --> 00:25:37,520
so to answer that question it sounds

705
00:25:41,350 --> 00:25:39,200
like we need somebody with expertise in

706
00:25:42,950 --> 00:25:41,360
both robotics and in

707
00:25:44,310 --> 00:25:42,960
tools

708
00:25:45,669 --> 00:25:44,320
so

709
00:25:48,549 --> 00:25:45,679
i would like to turn it over to my

710
00:25:50,470 --> 00:25:48,559
colleague joe mcguire jill it was the

711
00:25:51,669 --> 00:25:50,480
tool manager for the hubble servicing

712
00:25:54,390 --> 00:25:51,679
missions

713
00:25:57,190 --> 00:25:54,400

and she is a project manager for

714

00:25:58,470 --> 00:25:57,200

rrm here so jill would you uh help me

715

00:25:59,990 --> 00:25:58,480

answer this one

716

00:26:01,430 --> 00:26:00,000

i knew that uh

717

00:26:03,190 --> 00:26:01,440

ben prepped me to say he was going to

718

00:26:05,110 --> 00:26:03,200

turn a question over me i see he decided

719

00:26:08,870 --> 00:26:05,120

to give me the hard question save the

720

00:26:11,029 --> 00:26:08,880

easy ones for himself i'm no dummy

721

00:26:12,549 --> 00:26:11,039

so um just to make sure i understood

722

00:26:14,470 --> 00:26:12,559

what you asked the biggest difference

723

00:26:16,310 --> 00:26:14,480

between doing this in the ground in in

724

00:26:17,909 --> 00:26:16,320

orbit what we can expect the biggest

725

00:26:20,789 --> 00:26:17,919

difference is really in the orbital

726

00:26:23,190 --> 00:26:20,799

dynamics or how the contact dynamics

727

00:26:25,750 --> 00:26:23,200

on the ground we can control it

728

00:26:28,390 --> 00:26:25,760

how when we interface to this we can't

729

00:26:29,990 --> 00:26:28,400

100 percent control that in space and if

730

00:26:33,350 --> 00:26:30,000

you think about when we use the dexter

731

00:26:35,750 --> 00:26:33,360

robot it's on the end of the canadian

732

00:26:38,070 --> 00:26:35,760

arm 2. so you've got the dynamics in

733

00:26:40,710 --> 00:26:38,080

play between the canadian r2 and the

734

00:26:42,230 --> 00:26:40,720

spdm robot and then our tool so when you

735

00:26:43,269 --> 00:26:42,240

have all of that dynamics coming into

736

00:26:45,110 --> 00:26:43,279

play there's going to be some

737

00:26:47,669 --> 00:26:45,120

oscillations so

738

00:26:50,070 --> 00:26:47,679

coming trying to

739

00:26:53,190 --> 00:26:50,080

downplay that or figure out how that how

740

00:26:54,630 --> 00:26:53,200

you can react your to the spacecraft

741

00:26:57,029 --> 00:26:54,640

the interface when you touch it is the

742

00:27:00,390 --> 00:26:57,039

biggest thing so we built a contact

743

00:27:02,630 --> 00:27:00,400

dynamics facility at goddard where we

744

00:27:04,470 --> 00:27:02,640

simulate the dynamics that we expect to

745

00:27:06,950 --> 00:27:04,480

see on orbit so that when we practice on

746

00:27:08,549 --> 00:27:06,960

the ground we have those dynamics

747

00:27:11,350 --> 00:27:08,559

simulated so we know how the tool will

748

00:27:12,230 --> 00:27:11,360

react when it touches the spacecraft so

749

00:27:18,950 --> 00:27:12,240

the

750

00:27:21,110 --> 00:27:18,960

on orbit and we learn how

751
00:27:23,750 --> 00:27:21,120
the tools react to the interface we can

752
00:27:25,669 --> 00:27:23,760
then get ground characterization of our

753
00:27:27,110 --> 00:27:25,679
ground test bed or characterization of

754
00:27:28,470 --> 00:27:27,120
our ground test but excuse me so that

755
00:27:30,950 --> 00:27:28,480
will be the key thing is really the

756
00:27:33,269 --> 00:27:30,960
on-orbit dynamics that we don't have 100

757
00:27:34,389 --> 00:27:33,279
simulated on the ground

758
00:27:38,149 --> 00:27:34,399
all right thank you

759
00:27:41,750 --> 00:27:40,070
james dean with florida today can you

760
00:27:46,230 --> 00:27:41,760
identify the satellite that you're

761
00:27:48,310 --> 00:27:46,240
planning to service and and when and um

762
00:27:49,909 --> 00:27:48,320
when that time comes will will it is

763
00:27:51,350 --> 00:27:49,919

there a possibility you're going to you

764

00:27:52,870 --> 00:27:51,360

know add customers or is that just going

765

00:27:54,789 --> 00:27:52,880

to be a one-off test

766

00:27:55,590 --> 00:27:54,799

well it's um

767

00:28:00,470 --> 00:27:55,600

it's

768

00:28:03,669 --> 00:28:00,480

try to usurp commercial industry

769

00:28:05,350 --> 00:28:03,679

what we're trying to do here

770

00:28:07,510 --> 00:28:05,360

although we have looked at a whole

771

00:28:10,389 --> 00:28:07,520

different families of a family of

772

00:28:11,350 --> 00:28:10,399

satellites with different end effectors

773

00:28:12,389 --> 00:28:11,360

different

774

00:28:15,590 --> 00:28:12,399

feeling

775

00:28:18,070 --> 00:28:15,600

fuel valves different kinds of

776

00:28:19,909 --> 00:28:18,080

appendage deployment issues and so on

777

00:28:21,750 --> 00:28:19,919

what we're trying to do here is to

778

00:28:25,590 --> 00:28:21,760

demonstrate

779

00:28:27,830 --> 00:28:25,600

that we can in fact apply the technology

780

00:28:29,590 --> 00:28:27,840

so that no matter who does it and we're

781

00:28:32,310 --> 00:28:29,600

going to make this of data available to

782

00:28:35,029 --> 00:28:32,320

everybody that is all commercial

783

00:28:37,909 --> 00:28:35,039

industry that may want to

784

00:28:40,149 --> 00:28:37,919

leap off and and and start their their

785

00:28:41,269 --> 00:28:40,159

own ventures make that technology

786

00:28:44,310 --> 00:28:41,279

available

787

00:28:46,389 --> 00:28:44,320

allow them to understand what the risks

788

00:28:49,350 --> 00:28:46,399

are what the problems are

789

00:28:52,149 --> 00:28:49,360

and to in effect try to consolidate or

790

00:28:56,950 --> 00:28:54,870

reduce the risks of

791

00:28:59,269 --> 00:28:56,960

in-orbit repair and refueling and

792

00:29:01,269 --> 00:28:59,279

maintenance and super sinking to the

793

00:29:02,870 --> 00:29:01,279

greatest decree possible by being able

794

00:29:04,549 --> 00:29:02,880

to demonstrate

795

00:29:06,630 --> 00:29:04,559

on this

796

00:29:07,669 --> 00:29:06,640

kind of activity that we're running from

797

00:29:08,950 --> 00:29:07,679

station

798

00:29:11,110 --> 00:29:08,960

and therefore

799

00:29:14,549 --> 00:29:11,120

give everybody the encouragement that's

800

00:29:16,389 --> 00:29:14,559

necessary to get them rolling

801
00:29:17,990 --> 00:29:16,399
and there's all kinds of historical

802
00:29:20,230 --> 00:29:18,000
analogies

803
00:29:21,909 --> 00:29:20,240
and reasons for doing this if if one

804
00:29:23,909 --> 00:29:21,919
recalls

805
00:29:26,950 --> 00:29:23,919
what we all depend on today with

806
00:29:30,230 --> 00:29:26,960
blackberries and ipads and ipods and you

807
00:29:33,350 --> 00:29:30,240
know it is bandwidth is calm bandwidth

808
00:29:35,029 --> 00:29:33,360
and bandwidth is expanding exponentially

809
00:29:35,990 --> 00:29:35,039
year after year after year and the need

810
00:29:39,430 --> 00:29:36,000
for it

811
00:29:42,710 --> 00:29:39,440
and so what we're basically trying to do

812
00:29:45,350 --> 00:29:42,720
is to provide the encouragement

813
00:29:47,909 --> 00:29:45,360

to different operators and users to

814

00:29:50,710 --> 00:29:47,919

design their satellites and to

815

00:29:53,110 --> 00:29:50,720

perhaps design build and fly

816

00:29:54,710 --> 00:29:53,120

missions that can take care of the

817

00:29:56,710 --> 00:29:54,720

normal repair

818

00:29:58,470 --> 00:29:56,720

maintenance and refueling

819

00:29:59,909 --> 00:29:58,480

that would normally

820

00:30:02,549 --> 00:29:59,919

be required

821

00:30:04,310 --> 00:30:02,559

and without such a thing the satellites

822

00:30:06,470 --> 00:30:04,320

that are not getting this support or

823

00:30:09,350 --> 00:30:06,480

getting this kind of support would end

824

00:30:12,549 --> 00:30:09,360

in the end in failure would end

825

00:30:15,269 --> 00:30:12,559

their lives either abruptly or short of

826

00:30:18,389 --> 00:30:15,279

a full expectation of utilization

827

00:30:21,909 --> 00:30:18,399

so really this is a level of maturity

828

00:30:23,990 --> 00:30:21,919

for space in the space agency to help

829

00:30:26,149 --> 00:30:24,000

accelerate this maturity level and

830

00:30:28,389 --> 00:30:26,159

demonstrate this maturity level

831

00:30:31,750 --> 00:30:28,399

to give people

832

00:30:34,149 --> 00:30:31,760

like the telstar people in in the early

833

00:30:35,990 --> 00:30:34,159

60s the confidence

834

00:30:38,870 --> 00:30:36,000

to get going with a commercial

835

00:30:40,870 --> 00:30:38,880

communications satellite industry

836

00:30:44,310 --> 00:30:40,880

and that's what in fact has happened

837

00:30:47,190 --> 00:30:44,320

that's what nasa's role is give

838

00:30:51,269 --> 00:30:47,200

potential users the confidence

839

00:30:53,830 --> 00:30:51,279

to go ahead take the risks leap forward

840

00:30:57,029 --> 00:30:53,840

and for all of mankind

841

00:30:58,789 --> 00:30:57,039

to receive the benefits

842

00:31:00,789 --> 00:30:58,799

ten years from now the amount of

843

00:31:03,990 --> 00:31:00,799

bandwidth required

844

00:31:05,750 --> 00:31:04,000

if the rate of expansion of ipods and

845

00:31:08,710 --> 00:31:05,760

kindles and everything else

846

00:31:10,389 --> 00:31:08,720

in computation in the sky

847

00:31:11,990 --> 00:31:10,399

in the clouds

848

00:31:13,190 --> 00:31:12,000

if that expands at the rate we're going

849

00:31:16,070 --> 00:31:13,200

to have we're going to be a hundred

850

00:31:18,630 --> 00:31:16,080

times more in need 10 years from now of

851
00:31:21,350 --> 00:31:18,640
bandwidth than we have today can you

852
00:31:23,269 --> 00:31:21,360
imagine what that says about

853
00:31:25,590 --> 00:31:23,279
communication satellites and how to

854
00:31:27,750 --> 00:31:25,600
handle them and how to maintain them and

855
00:31:29,669 --> 00:31:27,760
how to protect them and how to use them

856
00:31:32,789 --> 00:31:29,679
and even more important

857
00:31:35,110 --> 00:31:32,799
we pay x number of fractions of a cent

858
00:31:36,630 --> 00:31:35,120
per data bit that comes down

859
00:31:37,990 --> 00:31:36,640
can you imagine

860
00:31:40,710 --> 00:31:38,000
what would happen

861
00:31:42,789 --> 00:31:40,720
if that if the numbers of

862
00:31:44,630 --> 00:31:42,799
communications bandwidth capability were

863
00:31:46,549 --> 00:31:44,640

to expand

864

00:31:49,190 --> 00:31:46,559

it would be a supply

865

00:31:51,590 --> 00:31:49,200

demand kind of ratio and you would lower

866

00:31:57,350 --> 00:31:51,600

the cost of operations and that's

867

00:32:02,389 --> 00:31:59,830

um so your intent is to

868

00:32:05,430 --> 00:32:02,399

basically turn over like an rrm type

869

00:32:07,110 --> 00:32:05,440

device to uh to a commercial user that

870

00:32:09,509 --> 00:32:07,120

would like integrate the technology

871

00:32:11,590 --> 00:32:09,519

something other than than dexter to the

872

00:32:13,830 --> 00:32:11,600

technology we we're going to make this

873

00:32:15,909 --> 00:32:13,840

technology

874

00:32:18,549 --> 00:32:15,919

yeah you wouldn't turn rrm over but

875

00:32:21,509 --> 00:32:18,559

you'd turn the technology to the type of

876

00:32:22,950 --> 00:32:21,519

tools the approach the lighting

877

00:32:25,590 --> 00:32:22,960

the cameras

878

00:32:29,190 --> 00:32:25,600

the tele robotic feedback those kinds of

879

00:32:32,310 --> 00:32:30,950

right right in the yellow shirt

880

00:32:34,630 --> 00:32:32,320

wait for the microphone please question

881

00:32:36,789 --> 00:32:34,640

for csa matthew does that mean that the

882

00:32:38,549 --> 00:32:36,799

canadian space agency and mcdonald while

883

00:32:42,070 --> 00:32:38,559

the technology of dexter would also be

884

00:32:43,909 --> 00:32:42,080

turned over to commercial affairs

885

00:32:46,789 --> 00:32:43,919

right now the plans is we're operating

886

00:32:48,149 --> 00:32:46,799

rm exactly like any other

887

00:32:49,590 --> 00:32:48,159

operation on the international space

888

00:32:51,110 --> 00:32:49,600

station we're

889

00:32:53,830 --> 00:32:51,120

you know participating in the flight

890

00:32:55,909 --> 00:32:53,840

control and the production of mission

891

00:32:58,149 --> 00:32:55,919

planning products and so on it will

892

00:33:00,630 --> 00:32:58,159

perform the analysis so basically the

893

00:33:02,950 --> 00:33:00,640

involvement of mcdonald that welder and

894

00:33:05,029 --> 00:33:02,960

associates as a primary contractor to

895

00:33:06,389 --> 00:33:05,039

csa for the international space station

896

00:33:07,430 --> 00:33:06,399

support they support us they provide us

897

00:33:09,269 --> 00:33:07,440

with the engineering support that's

898

00:33:11,269 --> 00:33:09,279

required to

899

00:33:13,430 --> 00:33:11,279

perform these tasks as we would for any

900

00:33:14,710 --> 00:33:13,440

other maintenance task onboard the space

901
00:33:16,549 --> 00:33:14,720
station

902
00:33:18,950 --> 00:33:16,559
in parallel uh what we're doing is that

903
00:33:21,110 --> 00:33:18,960
we're we have put up um

904
00:33:23,830 --> 00:33:21,120
there's a in works a next-generation

905
00:33:26,870 --> 00:33:23,840
cataract project where we're developing

906
00:33:28,710 --> 00:33:26,880
terrestrial prototypes for robots

907
00:33:31,750 --> 00:33:28,720
and defectors tools and so on but at

908
00:33:34,710 --> 00:33:31,760
this point it's it's uh basically uh

909
00:33:36,070 --> 00:33:34,720
the current state of our projects

910
00:33:37,269 --> 00:33:36,080
all right

911
00:33:40,950 --> 00:33:37,279
so a

912
00:33:45,350 --> 00:33:43,029
hi mark kirkman interspace news um

913
00:33:47,669 --> 00:33:45,360

actually a two-part question um in

914

00:33:49,509 --> 00:33:47,679

dealing with the uh or in regards to the

915

00:33:50,630 --> 00:33:49,519

space refueling do you kind of envision

916

00:33:52,789 --> 00:33:50,640

this uh

917

00:33:54,149 --> 00:33:52,799

using this initially at least with

918

00:33:55,830 --> 00:33:54,159

satellites that are at the end of their

919

00:33:57,909 --> 00:33:55,840

life cycle because i can foresee a

920

00:33:59,509 --> 00:33:57,919

scenario for instance you go up there

921

00:34:01,190 --> 00:33:59,519

with a satellite and you manipulate a

922

00:34:02,549 --> 00:34:01,200

valve that hasn't been operated since it

923

00:34:04,470 --> 00:34:02,559

left the ground and now all of a sudden

924

00:34:07,750 --> 00:34:04,480

you're you're leaking gas

925

00:34:09,589 --> 00:34:07,760

um also the second question would be is

926

00:34:11,190 --> 00:34:09,599

there any effort in the industry now i

927

00:34:13,270 --> 00:34:11,200

mean is it too early to kind of

928

00:34:15,270 --> 00:34:13,280

standardize these types of fittings so

929

00:34:17,349 --> 00:34:15,280

that as this technology has developed

930

00:34:18,470 --> 00:34:17,359

you can deal with the new spacecraft

931

00:34:20,629 --> 00:34:18,480

that are being launched are they

932

00:34:23,589 --> 00:34:20,639

standardizing the these fittings the

933

00:34:25,349 --> 00:34:23,599

fuel valves etc etc

934

00:34:26,550 --> 00:34:25,359

um

935

00:34:28,790 --> 00:34:26,560

from the point of view of

936

00:34:30,869 --> 00:34:28,800

standardization most of the valves that

937

00:34:32,869 --> 00:34:30,879

are manufactured and built today are

938

00:34:36,470 --> 00:34:32,879

very very

939

00:34:38,389 --> 00:34:36,480

much the same kinematic principles the

940

00:34:39,829 --> 00:34:38,399

only thing that's different about them

941

00:34:41,829 --> 00:34:39,839

is dimensions

942

00:34:43,349 --> 00:34:41,839

for the most part from a refueling

943

00:34:45,510 --> 00:34:43,359

perspective we notice that that

944

00:34:48,069 --> 00:34:45,520

commonality has happened in the

945

00:34:50,069 --> 00:34:48,079

aerospace industry over the last 30

946

00:34:53,030 --> 00:34:50,079

years 40 years

947

00:34:55,829 --> 00:34:53,040

is really maybe a driver for

948

00:34:58,790 --> 00:34:55,839

consolidation and cost control

949

00:35:02,470 --> 00:34:58,800

but there is very very difficult to try

950

00:35:05,990 --> 00:35:02,480

to standardize anything in space

951
00:35:08,870 --> 00:35:06,000
in this arena because every aerospace

952
00:35:11,510 --> 00:35:08,880
manufacturer of satellites

953
00:35:13,910 --> 00:35:11,520
has his own unique approach

954
00:35:15,990 --> 00:35:13,920
and no way no how do they ever want to

955
00:35:17,910 --> 00:35:16,000
give that approach up because it's

956
00:35:20,150 --> 00:35:17,920
endemic

957
00:35:22,870 --> 00:35:20,160
so where does that leave

958
00:35:24,950 --> 00:35:22,880
repair and maintenance in orbit which is

959
00:35:27,589 --> 00:35:24,960
really the heart of your question

960
00:35:30,230 --> 00:35:27,599
we have to be dexterous enough we have

961
00:35:33,190 --> 00:35:30,240
to be general purpose enough with the

962
00:35:35,990 --> 00:35:33,200
development of our tools

963
00:35:38,470 --> 00:35:36,000

so as to be able to demonstrate that you

964

00:35:39,349 --> 00:35:38,480

can do more than one straightforward

965

00:35:42,630 --> 00:35:39,359

task

966

00:35:44,790 --> 00:35:42,640

on more than one kind of satellite

967

00:35:48,230 --> 00:35:44,800

on more than one kind of fill and

968

00:35:52,150 --> 00:35:50,870

and perhaps maybe on more than one type

969

00:35:55,270 --> 00:35:52,160

of array

970

00:35:57,510 --> 00:35:55,280

or one type of communications antenna

971

00:36:00,710 --> 00:35:57,520

that didn't deploy

972

00:36:02,470 --> 00:36:00,720

now the mix is of how many satellites

973

00:36:03,430 --> 00:36:02,480

the last question the first question you

974

00:36:05,990 --> 00:36:03,440

asked

975

00:36:08,069 --> 00:36:06,000

was what about the old bird that's up

976
00:36:09,670 --> 00:36:08,079
there and you try to refuel it's been up

977
00:36:11,670 --> 00:36:09,680
there 20 years

978
00:36:13,990 --> 00:36:11,680
and you can't do it

979
00:36:16,950 --> 00:36:14,000
well the one thing you can do

980
00:36:18,550 --> 00:36:16,960
is you can supersync it with um

981
00:36:20,310 --> 00:36:18,560
with that kind of

982
00:36:22,470 --> 00:36:20,320
tow truck sort of capability you can

983
00:36:24,069 --> 00:36:22,480
take it out of orbit so to speak

984
00:36:24,950 --> 00:36:24,079
so to speak

985
00:36:28,230 --> 00:36:24,960
so

986
00:36:30,630 --> 00:36:28,240
those are the kinds of thought processes

987
00:36:33,430 --> 00:36:30,640
that one has to come to grips with when

988
00:36:36,630 --> 00:36:33,440

one starts to think about

989

00:36:41,829 --> 00:36:36,640

developing tow trucks in orbit

990

00:36:44,150 --> 00:36:41,839

that can take care of expensive assets

991

00:36:46,470 --> 00:36:44,160

that's key and one has to think about

992

00:36:49,030 --> 00:36:46,480

the ability to leave that asset

993

00:36:50,230 --> 00:36:49,040

leave that tow truck in orbit

994

00:36:51,109 --> 00:36:50,240

long enough

995

00:36:53,190 --> 00:36:51,119

for

996

00:36:55,430 --> 00:36:53,200

several or quite a few

997

00:36:57,670 --> 00:36:55,440

different spacecrafts that get into

998

00:36:59,270 --> 00:36:57,680

trouble to take advantage of it and it's

999

00:37:01,510 --> 00:36:59,280

not going to be able to be all things to

1000

00:37:02,470 --> 00:37:01,520

all people it's not going to be able to

1001
00:37:05,270 --> 00:37:02,480
be that

1002
00:37:08,230 --> 00:37:05,280
but there will be as a result enough

1003
00:37:09,349 --> 00:37:08,240
competition and enough interest i think

1004
00:37:11,990 --> 00:37:09,359
i feel

1005
00:37:14,150 --> 00:37:12,000
that you'll have more than one supplier

1006
00:37:15,990 --> 00:37:14,160
and that's all that's all very good i

1007
00:37:19,190 --> 00:37:16,000
mean you have today you have

1008
00:37:21,109 --> 00:37:19,200
dlr in germany that's looking at similar

1009
00:37:23,109 --> 00:37:21,119
approaches with deals

1010
00:37:25,829 --> 00:37:23,119
you have the japanese that have done

1011
00:37:27,910 --> 00:37:25,839
even some demonstration servicing

1012
00:37:30,790 --> 00:37:27,920
on some of their payloads

1013
00:37:33,270 --> 00:37:30,800

you have canada and mda that are very

1014

00:37:35,349 --> 00:37:33,280

much interested in doing that and yes

1015

00:37:37,030 --> 00:37:35,359

i'm sure we're going to have american

1016

00:37:39,670 --> 00:37:37,040

communications companies that are going

1017

00:37:42,150 --> 00:37:39,680

to stand up and take an interest

1018

00:37:46,550 --> 00:37:42,160

but that's all well and good where would

1019

00:37:51,990 --> 00:37:49,510

competition is wonderful

1020

00:37:53,670 --> 00:37:52,000

and that's the important message here

1021

00:37:55,430 --> 00:37:53,680

and what you have to do to get

1022

00:37:58,230 --> 00:37:55,440

competition started

1023

00:38:00,150 --> 00:37:58,240

is reduce the risks

1024

00:38:01,829 --> 00:38:00,160

that they're walking into

1025

00:38:03,109 --> 00:38:01,839

reduce the risk

1026
00:38:05,510 --> 00:38:03,119
and that's what

1027
00:38:07,589 --> 00:38:05,520
rrm represents

1028
00:38:09,510 --> 00:38:07,599
it's a risk reduction technology

1029
00:38:11,750 --> 00:38:09,520
demonstration

1030
00:38:14,150 --> 00:38:11,760
probably from a space station

1031
00:38:17,270 --> 00:38:14,160
perspective

1032
00:38:19,670 --> 00:38:17,280
the most practical demonstration

1033
00:38:22,710 --> 00:38:19,680
of the worth of station from an

1034
00:38:24,710 --> 00:38:22,720
applications perspective not medical

1035
00:38:27,030 --> 00:38:24,720
not physiological

1036
00:38:30,310 --> 00:38:27,040
not metallurgical

1037
00:38:33,589 --> 00:38:30,320
but applications what does it bring

1038
00:38:35,510 --> 00:38:33,599

as a demonstration to you and i 10 years

1039

00:38:38,630 --> 00:38:35,520

from now

1040

00:38:41,190 --> 00:38:38,640

that's the key that's the key we have to

1041

00:38:42,950 --> 00:38:41,200

have the ability to look forward

1042

00:38:45,270 --> 00:38:42,960

we have to look beyond today and

1043

00:38:46,550 --> 00:38:45,280

tomorrow and keep stretching the

1044

00:38:48,390 --> 00:38:46,560

technology

1045

00:38:50,790 --> 00:38:48,400

and that's what space station is about

1046

00:38:53,910 --> 00:38:50,800

it gives us that applications technology

1047

00:38:56,550 --> 00:38:53,920

capability to push the envelope to get

1048

00:38:59,430 --> 00:38:56,560

us out in front yes

1049

00:39:01,990 --> 00:38:59,440

one day we're going to fly

1050

00:39:04,310 --> 00:39:02,000

a neurosurgical robot that will do

1051

00:39:06,390 --> 00:39:04,320

operations on astronauts

1052

00:39:08,150 --> 00:39:06,400

from the ground

1053

00:39:09,910 --> 00:39:08,160

they do that today and it's called da

1054

00:39:12,470 --> 00:39:09,920

vinci

1055

00:39:15,190 --> 00:39:12,480

and and the canadians have one and i'm

1056

00:39:17,829 --> 00:39:15,200

at a loss to tell you what it called but

1057

00:39:22,069 --> 00:39:17,839

10 of our hospitals today in the united

1058

00:39:23,910 --> 00:39:22,079

states have da vinci robot surgical

1059

00:39:26,950 --> 00:39:23,920

instruments

1060

00:39:28,550 --> 00:39:26,960

are we going to have that 10 20 15 years

1061

00:39:30,310 --> 00:39:28,560

from now when we send our astronauts

1062

00:39:32,710 --> 00:39:30,320

away for a couple years

1063

00:39:35,670 --> 00:39:32,720

to distant locations

1064

00:39:38,790 --> 00:39:35,680

if we keep this up i think we will

1065

00:39:40,829 --> 00:39:38,800

but this is truly applications

1066

00:39:43,510 --> 00:39:40,839

demonstration

1067

00:39:46,150 --> 00:39:43,520

capability right take this uh gentleman

1068

00:39:47,910 --> 00:39:46,160

right here yes yeah i'm p i'm peter

1069

00:39:50,230 --> 00:39:47,920

wright with the canadian press um you

1070

00:39:52,630 --> 00:39:50,240

talked very very shortly about reducing

1071

00:39:54,069 --> 00:39:52,640

risks now over the past few years

1072

00:39:55,829 --> 00:39:54,079

we're seeing satellites starting to

1073

00:39:57,349 --> 00:39:55,839

crash into each other i just wonder if

1074

00:39:59,030 --> 00:39:57,359

there was any urgency to do this in

1075

00:40:01,109 --> 00:39:59,040

light of the fact that there are a lot

1076

00:40:03,109 --> 00:40:01,119

of satellites that are reaching their

1077

00:40:04,550 --> 00:40:03,119

uh best before date uh there are

1078

00:40:05,750 --> 00:40:04,560

satellites starting to crash into each

1079

00:40:07,589 --> 00:40:05,760

other there's a lot of concern about

1080

00:40:10,230 --> 00:40:07,599

that i wonder if that prompted you to

1081

00:40:12,309 --> 00:40:10,240

speed things up a little bit

1082

00:40:14,950 --> 00:40:12,319

i think that was one of the factors i

1083

00:40:17,109 --> 00:40:14,960

think clearly when those two satellites

1084

00:40:19,190 --> 00:40:17,119

collided that that clearly orbital

1085

00:40:21,670 --> 00:40:19,200

debris i think there was a another

1086

00:40:22,390 --> 00:40:21,680

satellite called galaxy 15 or something

1087

00:40:24,630 --> 00:40:22,400

that

1088

00:40:26,309 --> 00:40:24,640

temporarily drifted out of control and

1089

00:40:27,430 --> 00:40:26,319

all all the other communication

1090

00:40:29,670 --> 00:40:27,440

satellites

1091

00:40:30,790 --> 00:40:29,680

were jocking their positions and handing

1092

00:40:32,390 --> 00:40:30,800

off

1093

00:40:33,910 --> 00:40:32,400

calm responsibilities because they

1094

00:40:34,950 --> 00:40:33,920

wanted to get out of the way before they

1095

00:40:37,670 --> 00:40:34,960

got hit

1096

00:40:40,470 --> 00:40:37,680

i think all of those kinds of things are

1097

00:40:43,349 --> 00:40:40,480

what's going to happen tomorrow

1098

00:40:46,550 --> 00:40:43,359

and the day after and the day after

1099

00:40:48,069 --> 00:40:46,560

and the more satellites you put up there

1100

00:40:49,750 --> 00:40:48,079

which you're going to have to do to

1101
00:40:51,589 --> 00:40:49,760
cover bandwidth

1102
00:40:52,950 --> 00:40:51,599
you're going to have to do it

1103
00:40:55,030 --> 00:40:52,960
the more

1104
00:40:57,589 --> 00:40:55,040
probability there is that you're going

1105
00:40:58,710 --> 00:40:57,599
to need a tow truck

1106
00:41:00,470 --> 00:40:58,720
and

1107
00:41:03,910 --> 00:41:00,480
interestingly enough

1108
00:41:08,069 --> 00:41:03,920
probably more than one

1109
00:41:09,829 --> 00:41:08,079
few

1110
00:41:14,309 --> 00:41:09,839
and they're going to have to stay there

1111
00:41:18,150 --> 00:41:16,630
okay all right thank you uh i've got a

1112
00:41:21,510 --> 00:41:18,160
follow-up question

1113
00:41:22,950 --> 00:41:21,520

right here and i'll do that okay uh jim

1114

00:41:25,750 --> 00:41:22,960

siegel again from the celebration

1115

00:41:27,349 --> 00:41:25,760

independent uh with respect to these tow

1116

00:41:30,630 --> 00:41:27,359

trucks that you mentioned

1117

00:41:35,270 --> 00:41:30,640

uh roughly what time frame would you see

1118

00:41:36,790 --> 00:41:35,280

this happening 2025 2050

1119

00:41:39,349 --> 00:41:36,800

where these

1120

00:41:41,349 --> 00:41:39,359

these commercial tow trucks let's say

1121

00:41:43,670 --> 00:41:41,359

gerhard wanted us to start his own truck

1122

00:41:45,109 --> 00:41:43,680

truck company and use your technology

1123

00:41:47,670 --> 00:41:45,119

he's going to put it in space he's going

1124

00:41:49,349 --> 00:41:47,680

to go around and service satellites

1125

00:41:53,030 --> 00:41:49,359

we what kind of time frame are we

1126

00:41:53,040 --> 00:41:57,990

i wish you were here in 1984

1127

00:42:02,630 --> 00:42:00,950

you know i i can't i i think i think the

1128

00:42:04,550 --> 00:42:02,640

time frame is the next three or four

1129

00:42:06,790 --> 00:42:04,560

years five years

1130

00:42:09,829 --> 00:42:06,800

we're going to have to be there done

1131

00:42:12,309 --> 00:42:09,839

that and i maintain that by this kind of

1132

00:42:14,630 --> 00:42:12,319

technology when i say we it doesn't

1133

00:42:16,470 --> 00:42:14,640

necessarily have to be nasa it does not

1134

00:42:18,069 --> 00:42:16,480

have to could be commercial could be

1135

00:42:20,470 --> 00:42:18,079

commercial from any place around the

1136

00:42:23,109 --> 00:42:20,480

world i think the business base will

1137

00:42:27,190 --> 00:42:23,119

start to demonstrate itself

1138

00:42:30,390 --> 00:42:27,200

but don't forget i was here in 1984

1139

00:42:32,390 --> 00:42:30,400

and we had a screwy mission a very

1140

00:42:35,030 --> 00:42:32,400

never been done before mission

1141

00:42:36,710 --> 00:42:35,040

called the repair of solar max

1142

00:42:39,510 --> 00:42:36,720

does anybody remember that you weren't

1143

00:42:40,390 --> 00:42:39,520

born then oh some of you were

1144

00:42:42,630 --> 00:42:40,400

okay

1145

00:42:47,349 --> 00:42:42,640

she's nuts i always thought there was an

1146

00:42:52,309 --> 00:42:48,870

guess what

1147

00:42:55,430 --> 00:42:52,319

nobody but nobody ever envisioned

1148

00:42:57,670 --> 00:42:55,440

that we would capture solar max

1149

00:43:00,470 --> 00:42:57,680

with a robotic arm

1150

00:43:01,510 --> 00:43:00,480

nobody ever envisioned it and some

1151
00:43:03,430 --> 00:43:01,520
idiots

1152
00:43:06,069 --> 00:43:03,440
who had some forethought at goddard

1153
00:43:08,069 --> 00:43:06,079
decided that before they launched they

1154
00:43:10,710 --> 00:43:08,079
would put a grapple fixture on that

1155
00:43:12,230 --> 00:43:10,720
spacecraft but that spacecraft was not

1156
00:43:15,589 --> 00:43:12,240
going to be captured by that grapple

1157
00:43:17,750 --> 00:43:15,599
fixture no no no that was just a

1158
00:43:18,790 --> 00:43:17,760
risk mitigation device whatever you want

1159
00:43:20,950 --> 00:43:18,800
to call it

1160
00:43:23,030 --> 00:43:20,960
that was a contingency

1161
00:43:25,510 --> 00:43:23,040
no but when we tried it the

1162
00:43:26,790 --> 00:43:25,520
old-fashioned way we discovered contact

1163
00:43:28,950 --> 00:43:26,800

dynamics

1164

00:43:31,109 --> 00:43:28,960

like we had never seen them before

1165

00:43:32,550 --> 00:43:31,119

involving humans and free-flying

1166

00:43:34,230 --> 00:43:32,560

spacecrafts

1167

00:43:38,230 --> 00:43:34,240

and guess what

1168

00:43:40,630 --> 00:43:38,240

it was solved by a robotic operation

1169

00:43:44,470 --> 00:43:40,640

of something called the canada arm for

1170

00:43:45,910 --> 00:43:44,480

the first time and after that guess what

1171

00:43:47,829 --> 00:43:45,920

we never

1172

00:43:49,670 --> 00:43:47,839

bothered to deal with capture of

1173

00:43:51,349 --> 00:43:49,680

spacecrafts any other way with robotics

1174

00:43:54,790 --> 00:43:51,359

so technology

1175

00:43:56,790 --> 00:43:54,800

is there technology is coming the issue

1176

00:43:58,710 --> 00:43:56,800

is how do we apply it

1177

00:44:01,589 --> 00:43:58,720

and how do we demonstrate its

1178

00:44:03,430 --> 00:44:01,599

application so that it minimizes risk

1179

00:44:05,430 --> 00:44:03,440

rrm is that way

1180

00:44:07,829 --> 00:44:05,440

and there'll be other missions

1181

00:44:08,550 --> 00:44:07,839

like rrm that'll come after that that

1182

00:44:10,870 --> 00:44:08,560

can

1183

00:44:14,630 --> 00:44:10,880

that will drive from station the ability

1184

00:44:16,069 --> 00:44:14,640

to demonstrate reduction of risk

1185

00:44:18,390 --> 00:44:16,079

all right we're but just about out of

1186

00:44:20,150 --> 00:44:18,400

time uh real quick can you get a

1187

00:44:21,750 --> 00:44:20,160

question really really quick randy

1188

00:44:24,390 --> 00:44:21,760

atwood again was uh spacecraft

1189

00:44:28,630 --> 00:44:24,400

interactive uh also back in 1984 on the

1190

00:44:31,109 --> 00:44:28,640

13th mission 41g there was a an eva and

1191

00:44:32,790 --> 00:44:31,119

there was a demonstration of refueling

1192

00:44:34,790 --> 00:44:32,800

can you did were there any lessons

1193

00:44:36,150 --> 00:44:34,800

learned from that or any applications

1194

00:44:38,950 --> 00:44:36,160

from that

1195

00:44:43,190 --> 00:44:38,960

the biggest one of all was five hubble

1196

00:44:49,750 --> 00:44:46,230

recovery mission right after deployment

1197

00:44:52,150 --> 00:44:49,760

cincom4 intelsat six

1198

00:44:53,910 --> 00:44:52,160

west arm palapa

1199

00:44:55,750 --> 00:44:53,920

there's a total of 11.

1200

00:44:57,670 --> 00:44:55,760

yes we learned a lot and i think we're

1201

00:44:59,910 --> 00:44:57,680

going to learn a lot from here

1202

00:45:02,630 --> 00:44:59,920

okay we're running out of time

1203

00:45:04,150 --> 00:45:02,640

if you've got more questions we can

1204

00:45:05,589 --> 00:45:04,160

deal with the questions a little bit

1205

00:45:09,030 --> 00:45:05,599

later you'll have a chance to talk with

1206

00:45:11,349 --> 00:45:09,040

uh with seppie and ben and the module

1207

00:45:13,430 --> 00:45:11,359

affectionately known as rosie so that

1208

00:45:15,190 --> 00:45:13,440

concludes our demonstration for today

1209

00:45:17,670 --> 00:45:15,200

the next event on nasa tv is the

1210

00:45:19,990 --> 00:45:17,680

multi-purpose crew vehicle demonstration

1211

00:45:21,349 --> 00:45:20,000

tomorrow morning at 9am and for more